Series PD

Quick Start Guide

Ethernet-Enabled Temperature/Process Controller

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Safety Information
We use note, caution and warning symbols throughout this book to draw your attention to important operational and safety information.
A “NOTE” marks a short message to alert you to an important detail.
A “CAUTION” safety alert appears with information that is important for protecting your equipment and performance. Be especially careful to read and follow all cautions that apply to your application.
A “WARNING” safety alert appears with information that is important for protecting you, others and equipment from damage. Pay very close attention to all warnings that apply to your application.
The safety alert symbol, ! (an exclamation point in a triangle) precedes a general CAUTION or WARNING statement.
The electrical hazard symbol, △ (a lightning bolt in a triangle) precedes an electric shock hazard CAUTION or WARNING safety statement.

Technical Assistance
If you encounter a problem with your Watlow controller, review your configuration information to verify that your selections are consistent with your application: inputs, outputs, alarms, limits, etc. If the problem persists, you can get technical assistance from your local Watlow representative (see back cover), by e-mailing your questions to wintechsupport@watlow.com or by dialing +1 (507) 494-5656 between 7 a.m. and 5 p.m., Central Standard Time (CST). Ask for an Applications Engineer. Please have the following information available when calling:
• Complete model number
• Quick Start Guide or User’s Manual
• Computer Hardware / Software Configuration

Warranty
The Series PD is manufactured by ISO 9001-registered processes and is backed by a three-year warranty.

Return Material Authorization (RMA)
1. Call Watlow Customer Service, (507) 454-5300, for a Return Material Authorization (RMA) number before returning any item for repair. We need this information:
• Ship to address
• Contact name
• Method of return shipment
• Detailed description of the problem
• Name and phone number of person returning the product.

2. Prior approval and an RMA number, from the Customer Service Department, is needed when returning any unused product for credit. Make sure the RMA number is on the outside of the carton, and on all paperwork returned. Ship on a Freight Prepaid basis.

3. After we receive your return, we will examine the unit and try to verify the reason for the return.

4. In cases of manufacturing defect, we will enter a repair order, replacement order or issue credit for material returned.

5. To return products that are not defective, goods must be be in new condition, in the original boxes and they must be returned within 120 days of receipt. A 20 percent restocking charge is applied for all returned stock controls and accessories.

6. If the unit is unrepairable, it will be returned to you with a letter of explanation.

7. Watlow reserves the right to charge for no trouble found (NTF) returns.

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**Overview**

The Series PD controller is a DIN rail mounted, general purpose industrial PID temperature/process controller. The Series PD is available in single and dual channel versions and features an embedded web server to provide an easy to use interface for configuration and monitoring of processes. The controller also features several popular communications protocols to facilitate easy integration into most existing process management systems.

The Series PD accepts thermocouple, RTD and process signal control inputs and also features optional auxiliary digital or current transformer (CT) inputs. Up to four control or event (alarm) outputs can be selected on either the single or dual channel versions.

Advanced features of the Series PD controllers include internal data logging of key control parameters, smart sensor technology, heater burn out detection and an enhanced control algorithm.

The SERIES PD controller is backed by a three-year warranty from Watlow Winona and is UL® 508, C-UL®, CSA and CE approved.

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**Figure 2 — Series PD inputs and outputs.**
Figure 3 — Series PD dimensions

Caution: Maintain the correct spacing between rows of controllers to allow sufficient air circulation and installation clearance. Failure to do so could result in damage to equipment.
Mounting the Series PD

Figure 4a — Mounting

1. Push unit in and down to catch rail hook on top of rail.
2. Rotate bottom of unit toward rail.
3. Rail clasp will audibly “snap” into place. If the Series PD does not snap into place, check to see if the rail is bent.

Removing the Series PD

Figure 4b — Removal

1. Press down on back of the Series PD until the bottom hook clears the rail.
2. Rotate bottom up and away from rail.
Series PD Connector Locations

Two connectors on the bottom of the unit provide connection points for the input power, inputs and outputs. These connectors are removable and each terminal position is numbered.

The RJ-45 connector is located on the top of the Series PD to allow connection to an Ethernet network.

Input and Output Connectors

![Input and Output Connectors](image1.png)

Ethernet RJ-45 Connector

![Ethernet RJ-45 Connector](image2.png)
Warning: Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Warning: If high voltage is applied to the controller, irreversible damage will occur.

Isolation Blocks
There are no electrical connections between these blocks

- Analog Input 1
- Digital Inputs
- Current Transformer Inputs

- Analog Input 2

- Control Outputs
- Alarm Outputs
- Retransmit Outputs

- Communications

Relay outputs (mechanical and solid-state) provide isolation through their relay contacts. Each relay output is isolated from the blocks above and is isolated from other relay outputs.

The model number for each output option appears with its wiring diagram. Check the label on the controller and compare your model number to those shown here and to the model number breakdown in the Appendix of this manual.

All outputs are referenced to a de-energized state.

All wiring and fusing must conform to the National Electric Code and to any locally applicable codes as well.

Figure 6a — Power Wiring
(all model numbers)

- Nominal voltage: 24V≈ (ac/dc)

![Power Wiring Diagram](image-url)
Warning: Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Figure 7a — Thermocouple Input 1
(all model numbers)
Thermocouples are polarity sensitive. The negative lead (usually red) must be connected to terminal 9.
- Input impedance: >20 MΩ

Figure 7b — Thermocouple Input 2
PD
Thermocouples are polarity sensitive. The negative lead (usually red) must be connected to terminal 5.
- Input impedance: >20 MΩ
- Input 2 isolated from Input 1

Figure 7c — 2-Wire RTD Input 1 (100 Ω DIN curve 0.00385 Ω/°C)
(all model numbers)
Terminals 9 and 11 must be shorted for a two-wire RTD.
- Nominal excitation current: 250 µA

Figure 7d — 3-Wire RTD Input 1 (100 Ω DIN curve 0.00385 Ω/°C)
(all model numbers)
The S1 lead (usually white) must be connected to terminal 10.
- Nominal excitation current: 250 µA
Warning: Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

**WARNING:** Process input may not have sensor break protection. Outputs can remain full on.

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**Figure 8a — 2-Wire RTD Input 2 (100 Ohm DIN curve 0.00385 Ohm/°C)**

PD

Terminals 5 and 7 must be shorted for a two-wire RTD.

- Nominal excitation current: 250 µA

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**Figure 8b — 3-Wire RTD Input 2 (100 Ohm DIN curve 0.00385 Ohm/°C)**

PD

The S1 lead (usually white) must be connected to terminal 6.

- Nominal excitation current: 250 µA

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**Figure 8c — Input 1, 0 to 10V (dc) Process Input**

(all model numbers)

- Input impedance 20 kOhm, dc only

---

**Figure 8d — Input 2, 0 to 10V (dc) Process Input**

- Input impedance 20 kOhm, dc only
- Input 2 isolated from Input 1
Warning: Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

WARNING: Process input may not have sensor break protection. Outputs can remain full on.

---

**Figure 9a — Input 1, 0 to 20 mA Process Input**
(all model numbers)
- Input impedance 100 Ω, dc only
- Controller does not supply power for the current loop

![Diagram of Input 1](image)

**Figure 9b — Input 2, 0 to 20 mA Process Input**
- Input impedance 100 Ω, dc only
- Controller does not supply power for the current loop
- Input 2 isolated from Input 1

![Diagram of Input 2](image)

**Dual Digital Inputs**
- Input impedance 10kΩ, dc only
- Input 2 isolated from Input 1

**Figure 9c — Voltage input**
- 0-1V= (dc) Event Input Low State
- 2-36V= (dc) Event Input High State

![Diagram of Voltage Input](image)

**Figure 9d — Contact closure**
- 0-2kΩ Event Input Low State
- > 7kΩ Event Input High State

![Diagram of Contact Closure](image)
Warning:
Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Note: Current transformer (CT) must be purchased separately.

Note: A current transformer input cannot be associated with a process output on Output 1 or 3.

Dual Current Transformer (CT) Inputs

- Input impedance 100Ω, Vac only.

The current transformer (CT) must be purchased separately. Watlow CT part number is 16-0246 (up to 50 amps).

Systems that are more than 50 amps need an interstage transformer. For example, if you use a 300 amp CT, part number 16-0073, and an interstage transformer, part number 16-0176, the 300 amp CT provides a 5 amp signal to the interstage transformer. In turn, the interstage transformer provides a 20 mA maximum signal to the controller.

Single phase current sensing up to 300 amp
Warning: Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Note: Current transformer (CT) must be purchased separately.

Note: A current transformer input cannot be associated with a process output on Output 1 or 3.

Note: Install a 1kΩ pull-down resistor for each digital input using voltage inputs.

Note: Install a 10kΩ pull-up resistor for each digital input using contact closure inputs.

Figure 11a — Three Phase using Two Current Transformers

One Digital Input and One Current Transformer Input

Digital Input 1
• Input impedance 10kΩ, dc only

Figure 11b — Voltage input
0-1V = (dc) Event Input Low State
2-36V = (dc) Event Input High State

Figure 11c — Contact closure
0-2kΩ Event Input Low State
> 7kΩ Event Input High State

Add a 1kΩ pull down resistor for each active input

Contact Closure (add a 10kΩ pull up resistor for each active input)
**Warning:**
Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

**Note:** Current transformer (CT) must be purchased separately.

**Note:** A process output cannot be installed on Output 1 or 3 when using current transformer input.

Figure 12a — **Current Transformer Input 2, Single Phase**
- Input impedance 100Ω, Vac only

The current transformer must be purchased separately. Watlow current transformer part number is 16-0246 (up to 50 amps).

Systems that are more than 50 amps need an interstage transformer. For example, if you use a 300 amp current transformer, part number 16-0073, and an interstage transformer, part number 16-0176, the 300 amp current transformer provides a 5 amp signal to the interstage transformer. In turn, the interstage transformer provides a 20 mA maximum signal to the controller.

**Figure 12b — Current Transformer Input 2, Three Phase**

3-phase current sensing up to 300 amp
Warning:
Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Quencharc Note:
Switching pilot duty loads (relay coils, solenoids, etc.) with the mechanical relay or solid-state relay output options requires use of an R.C. suppressor.

Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

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**Figure 13a — Output 1 Mechanical Relay**

- Form A contact
- 2 A, resistive
- 125 VA pilot duty, 120/240V~ (ac), inductive
- 240V~ (ac) maximum
- 30V (dc) maximum
- See Quencharc note
- For use with ac or dc
- Minimum load current 10 mA
- Output does not supply power

**Figure 13b — Output 1 Solid-state Relay**

- Form A contact
- 0.5 A, resistive
- 20 VA pilot duty, 120/240V~ (ac), inductive
- 24 to 240V~ (ac)
- See Quencharc note
- Minimum load current 10 mA
- Maximum leakage current 100 µA
- Not for use with direct current (dc)
- Output does not supply power

**Figure 13c — Output 1 Switched DC**

- Supply current 30 mA= (dc) maximum
- Supply voltage 24V= (dc)
- Not recommended for switching mechanical relays
- Output supplies power
Warning: Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Quencharc Note: Switching pilot duty loads (relay coils, solenoids, etc.) with the mechanical relay or solid-state relay output options requires use of an R.C. suppressor.

Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

Note: A current transformer input is not available if Output 1 or 3 is a process output.

**Figure 14a — Output 1 Open Collector**
PD_ _ - C_ _ _ _ _ _ _
- Maximum current sink 250 mA (dc)
- Maximum supply voltage 42V (dc)
- Output does not supply power

**Figure 14b — Output 1 Process**
PD_ _ - F_ _ _ _ _ _ _
- Analog output is scalable between 0 to 10V (dc) or 0 to 20 mA (dc)
- Load capability: voltage 1 kΩ minimum; current 800 Ω maximum
- Output supplies power
- Cannot use voltage and current output at the same time

**Figure 14c — Output 2 Mechanical Relay**
PD_ _ - _ E_ _ _ _ _ _
- Form C contacts
- 2 A, resistive
- 125 VA pilot duty, 120/240V~ (ac), inductive
- 240V~ (ac) maximum
- 30V (dc) maximum
- See Quencharc note
- For use with ac or dc
- Minimum load current: 10 mA
- Output does not supply power
Warning: Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Quencharc Note: Switching pilot duty loads (relay coils, solenoids, etc.) with the mechanical relay or solid-state relay output options requires use of an R.C. suppressor.

Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

Figure 15a — Output 2 Solid-state Relay

- Form A contact
- 0.5 A, resistive
- 20 VA pilot duty, 120/240V~ (ac), inductive
- 24 to 240V~ (ac)
- See Quencharc note
- Minimum load current 10mA
- Maximum leakage current 100µA
- Not for use with direct current (dc)
- Output does not supply power

Figure 15b — Output 2 Switched DC

- Maximum supply current 30 mA (dc)
- Supply voltage 24V= (dc)
- Not recommended for switching mechanical relays
- Output supplies power

Figure 15c — Output 2 Open Collector

- Maximum current sink 250 mA (dc)
- Maximum supply voltage 42V= (dc)
- Output does not supply power
Warning:
Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Quencharc Note:
Switching pilot duty loads (relay coils, solenoids, etc.) with the mechanical relay or solid-state relay output options requires use of an R.C. suppressor.

Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

Figure 16a — Output 3 Mechanical Relay
PD_ _ _ _ _ J_ _ _ _ _
• Form A contact
• 2 A, resistive
• 125 VA pilot duty, 120/240V~ (ac), inductive
• 240V~ (ac) maximum
• 30V= (dc) maximum
• See Quencharc note
• For use with ac or dc
• Minimum load current: 10 mA
• Output does not supply power

Figure 16b — Output 3 Solid-state Relay
PD_ _ _ _ _ K_ _ _ _ _
• Form A contact
• 0.5 A, resistive
• 20 VA pilot duty, 120/240V~ (ac), inductive
• 24 to 240V~ (ac)
• See Quencharc note
• Minimum load current 10 mA
• Maximum leakage current 100 µA
• Not for use with direct current (dc)
• Output does not supply power

Figure 16c — Output 3 Switched DC
PD_ _ _ _ _ C_ _ _ _ _
• Maximum supply current 30 mA= (dc)
• Supply voltage 24V= (dc)
• Not for switching mechanical relays
• Output supplies power
Warning: Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Quencharc Note: Switching pilot duty loads (relay coils, solenoids, etc.) with the mechanical relay or solid-state relay output options requires use of an R.C. suppressor.

Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

Note: A current transformer input is not available if Output 1 or 3 is a process output.

Figure 17a — Output 3 Open Collector

- Maximum current sink 250 mA (dc)
- Maximum supply voltage 42V (dc)
- Output does not supply power

Figure 17b — Output 3 Process

- Analog output scalable from 0 to 10V (dc) or 0 to 20 mA (dc)
- Load capability: voltage, 1 kΩ minimum; current, 800 Ω maximum
- Output supplies power
- Cannot use voltage and current output at the same time

Figure 17c — Output 4 Mechanical Relay

- Form C contacts
- 2 A, resistive
- 125 VA pilot duty, 120/240V (ac), inductive
- 240V (ac) maximum
- 30V (dc) maximum.
- See Quencharc note
- For use with ac or dc
- Minimum load current: 10 mA
- Output does not supply power
Warning:
Use National Electric (NEC) or other country-specific standard wiring and safety practices when wiring and connecting this controller to a power source and to electrical sensors or peripheral devices. Failure to do so may result in damage to equipment and property, and/or injury or loss of life.

Quencharc Note:
Switching pilot duty loads (relay coils, solenoids, etc.) with the mechanical relay or solid-state relay output options requires use of an R.C. suppressor.

Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

Figure 18a — Output 4 Solid-state Relay
PD_ _ _ _ _ _ K _ _ _ _
- Form A contact
- 0.5 A, resistive
- 20 VA pilot duty, 120/240V~ (ac), inductive
- 24 to 240V~ (ac)
- See Quencharc note
- Minimum load current 10mA
- Maximum leakage current 100µA
- Not for use with direct current (dc)
- Output does not supply power

Figure 18b — Output 4 Switched DC
PD_ _ _ _ _ _ C _ _ _ _
- Maximum supply current 30 mA (dc)
- Supply voltage 24V= (dc)
- Not recommended for switching mechanical relays
- Output supplies power

Figure 18c — Output 4 Open Collector
PD_ _ _ _ _ _ C _ _ _ _
- Maximum current sink 250 mA (dc)
- Maximum supply voltage 42V= (dc)
- Output does not supply power
The Series PD controller may have up to nine LED indicator lights to help you monitor the status of input power, Ethernet functions, input errors and outputs status. These LEDs can provide a quick visual indication of basic controller functions.

**Power**
Green light stays lit when the power is on.
- If not lit or flashing, check your power source.

**Ethernet Link:**
Green light is lit if the Ethernet cable is correctly wired and connected to a 10BaseT port.
- If not lit, check for the correct RJ-45 cable and switch/hub speed.

**Ethernet Activity**
Green light is lit when communication activity occurs.

(1) **Input Error**
Red light is lit if there is a sensor problem on Input 1. Lights momentarily after power up.
- If it stays lit:
  - Verify the sensor wiring, polarity and function.
  - Rewire or replace as necessary.

(2) **Input Error**
Red light is lit if there is a sensor problem on Input 2. Lights momentarily after power up.
- If it stays lit:
  - Verify the sensor wiring, polarity and function.
  - Rewire or replace as necessary.

(1) **Output**
Red light is lit or flashes when control Output 1 is active. If it does not light up, the output is not active. The output may be configured as an event (alarm) or control.

(2) **Output**
Red light is lit or flashes when control Output 2 is active. If it does not light up, the output is not active. The output may be configured as an event (alarm) or control.

(3) **Output**
Red light is lit or flashes when control Output 3 is active. If it does not light up, the output is not active. The output may be configured as an event (alarm) or control.

(4) **Output**
Red light is lit or flashes when control Output 4 is active. If it does not light up, the output is not active. The output may be configured as an event (alarm) or control.

**Address Field**
Record the unit's Device Name in erasable marker here. For example, PD012345.

Figure 18 — Series PD LED Indicator Lights
Network security is a critical issue for any network. Be sure to work with your network administrator to ensure that you follow best security practices to ensure a secure network environment. Here are some items to consider when installing Ethernet based controls on any network.

- Use private IP addresses.
- Separate the process network(s) from business network(s).
- If external access is required, then have a single point of access to the process network.
- External access points should be protected by a firewall.
- External access points should be protected by a layer 3 switch.
- Access to the Internet should be indirect, going through an access point to the business network on the way.
- Separate processes or cells using VLANs.
- Run virus protection software on all PC’s on the process network.

Using an HTTP Browser such as Microsoft Internet Explorer 4.0 or Netscape Navigator 4.0 or higher, you may access the Series PD and view controller parameters via an onboard Web (HTTP) server.

The Series PD supports full product configuration and monitoring of runtime parameters via MODBUS TCP over TCP/IP using a third party software package such as Lookout™, created and sold by National Instruments.

The 10BaseT Ethernet connection supports the TCP/IP stack. At the application layer it has an HTTP (web) and Modbus server. The HTTP server provides a means of changing runtime parameters via HTML. The TCP/IP stack supports DHCP client, AutoIP, static IP, DNS client, and Netbios name resolution. The 10BaseT connector is an RJ45 per the IEEE 802.3 specification.

**Getting Started**

1. Connect the Series PD to your computer’s Ethernet port using a cross-wired RJ45 cable or connect the Series PD to a switch/hub or network using a straight wired RJ45 Category 5 cable. The Series PD is limited to a 10BaseT connection and will not work on an Ethernet port set for 100BaseT only. Use of a 10/100 switch/hub will overcome this issue if your PC has only a 100BaseT port.

2. Wire a 24V (ac/dc) power supply to the Series PD power terminals. See wiring section.

3. Wire sensor inputs and controller outputs. See wiring section.

4. Power up the controller, switch/hub and PC.

5. Start your Internet browser. Enter the Browse at address of the Series PD into the browser’s address field. See figure on next page for the Browse at address location on the left side label. Two different Netbios names may be used to access the Series PD. Either PDxxxxxx, where xxxxxx is the first six digits of the serial number, located on the left side label, or WATxxxxxx, where xxxxxx is the last six digits of the Series PD MAC address. The MAC address is also printed on the left side label of the Series PD in the form xx:xx:xx:xx:xx. See figure on next page.

**Note:** If you are not using a DHCP server, it may take several minutes for both the Series PD and your computer to get their IP addresses.
6. When you select any page other than Monitor Page, you are prompted to enter a Network Security user name and password. The defaults are:

   user name - new
   password - user

7. Once you enter the user name and password you can access the other controller pages. If you browse another address or close your browser, you will be required to enter this information again.

8. To change security level passwords, go to the Configuration Page and click on Security.

9. To configure the Series PD, go to the Configuration Page.

   Note: The controller leaves the factory with all inputs, outputs and control loops set to off.
   Go through each Configuration Page screen and make the appropriate selections for your application. Click the Submit button at the bottom of each page.

   Note: Be sure to click the Submit button at the bottom of any Configuration Page screen to send your changes to the controller. Changes are not entered into the controller until you submit them.

9. Select the Monitor Page. Your process values and set points will be displayed. You can change controller set point and the mode of operation, auto or manual. Select the parameter value you want to change by double clicking or highlighting it, enter the new parameter value and press the Enter key. This will send the Series PD the new value and refresh the Monitor Page screen.

   Caution: Information on the Monitor Page, including alarms and errors, is not automatically refreshed. You must click the refresh link on the Monitor page to request the latest controller information. The Monitor Page is refreshed anytime you change set point or auto/manual mode.

Network Services

The Series PD supports DHCP client, autoIP, and static IP for address assignment. Normally you will not need to make any changes. The user is able to configure preferences as to which services are used if available. Intelligence is employed within the gateway to revert to backup IP assignment methods if the primary method is unavailable.

When using autoIP, the Series PD starts with the IP address 169.254.10.10. If this address is already in use, it will randomly attempt other addresses in the 169.254.XX.XX subnet. As with any IP networking device, the IP address assigned to the Series PD must be compatible with the network it is physically connected to.

Note: If you are using autoIP, it may take several minutes for both the Series PD and your computer to get their IP addresses.

The Series PD does support DNS client and Netbios name resolution. Configuration information may be entered at the Network Display Setup page.
## Troubleshooting

<table>
<thead>
<tr>
<th>Indication</th>
<th>Probable Cause(s)</th>
<th>Corrective Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power LED not lit. Controller appears dead. No communications to PC.</td>
<td>• Power supply switch off. • Fuse blown. • Breaker tripped. • Safety interlock door switch activated. • Separate system limit control latched. • Wiring incorrect or open. • Power supply voltage incorrect. • Defective controller.</td>
<td>• Turn switch on. • Replace fuse (check cause of failure). • Reset breaker (check cause of failure). • Close door. • Reset limit controller. • Check wiring. • Verify input power • Repair or replace controller.</td>
</tr>
<tr>
<td>Ethernet Link LED not lit. No communications to PC.</td>
<td>• Incorrect cable. • Defective PC or switch/hub. • Defective controller.</td>
<td>• Replace cable - use straight cable for switch/hub, cross cable for direct connection to PC. • Replace Ethernet port on PC or switch/hub. • Repair or replace controller.</td>
</tr>
<tr>
<td>Ethernet Link Activity LED not lit. No communication to PC.</td>
<td>• Incorrect IP address assignment. • Incorrect PC set-up. • Defective controller.</td>
<td>• Assign same logical address. Fixed IP address may have been assigned. • Ensure Microsoft Client and Netbios is loaded. • Repair or replace controller.</td>
</tr>
<tr>
<td>Input Error LED lit. Sensor over range, under range message on PC.</td>
<td>• Open sensor. • Shorted sensor. • Process has exceeded operating range. • Incorrect sensor configuration. • Defective controller.</td>
<td>• Replace sensor. • Repair wiring or replace sensor. • Operate controller within sensor operation range. • Configure Analog Input to correct sensor type. • Repair or replace controller.</td>
</tr>
<tr>
<td>Ambient error message on PC.</td>
<td>• Temperature is less than 0°C (32°F) or greater than 65°C (149°F). • Controller calibration is incorrect or corrupt. • Defective controller.</td>
<td>• Regulate temperature in cabinet. • Recalibrate controller. • Repair or replace controller.</td>
</tr>
<tr>
<td>No Output from controller. Output always active. Output always inactive.</td>
<td>• Incorrect wiring. • DC voltage used with AC output. • External voltage is not supplied for appropriate outputs. • Wrong output choice. • Incorrect configuration. • Power limit is in effect or in open loop mode. • Defective controller.</td>
<td>• Correct wiring, see wiring section. • K output is for AC control, C &amp; F output is for DC control. • Wire correct voltage to be controlled for appropriate output, see wiring section. • Replace controller with correct outputs. • Configure Control Loop, PID, and Output. • Adjust power limit or change to closed loop mode. • Repair or replace controller.</td>
</tr>
<tr>
<td>Indication</td>
<td>Probable Cause(s)</td>
<td>Corrective Action</td>
</tr>
<tr>
<td>---------------------------------------------------------------------------</td>
<td>----------------------------------------------------------------------------------</td>
<td>----------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Alarm will not activate or clear.</td>
<td>• Controller is in Error condition.</td>
<td>• Determine cause of error and correct.</td>
</tr>
<tr>
<td></td>
<td>• Alarm is in latched setting.</td>
<td>• Wait for process to return to normal and acknowledge alarm.</td>
</tr>
<tr>
<td></td>
<td>• Alarm is silenced.</td>
<td>• Wait for process to return to normal and alarm will work correctly.</td>
</tr>
<tr>
<td></td>
<td>• Incorrect configuration.</td>
<td>• Configure Alarm, Alarm Set Point, Hysteresis, Silencing and Latching.</td>
</tr>
<tr>
<td></td>
<td>• Incorrect wiring.</td>
<td>• Correct wiring.</td>
</tr>
<tr>
<td></td>
<td>• Wrong output type.</td>
<td>• Replace controller with correct output type.</td>
</tr>
<tr>
<td></td>
<td>• Defective controller.</td>
<td>• Repair or replace controller.</td>
</tr>
<tr>
<td>Controller’s process value reading is decreasing as the actual process is increasing.</td>
<td>• Thermocouple is reversed wired.</td>
<td>• Check thermocouple wire for correct polarity.</td>
</tr>
<tr>
<td></td>
<td>• Analog voltage or current input scaling is reversed.</td>
<td>• Configure correct scaling on Input page.</td>
</tr>
<tr>
<td>Controller does not control close enough to set point.</td>
<td>• PID values incorrect.</td>
<td>• Tune controller (Auto Tune or Manual Tune).</td>
</tr>
<tr>
<td></td>
<td>• Cycle times incorrect.</td>
<td>• Set cycle time to match hardware on Control Loop.</td>
</tr>
<tr>
<td></td>
<td>• Heat or cooling capacity incorrectly sized for application.</td>
<td>• Size energy sources to match load.</td>
</tr>
<tr>
<td></td>
<td>• Incorrect sensor placement.</td>
<td>• Place sensor in optimal location.</td>
</tr>
<tr>
<td></td>
<td>• Controller is in Manual mode (open loop).</td>
<td>• Change to Auto mode (closed loop) on Monitor page.</td>
</tr>
<tr>
<td></td>
<td>• Control loop action configured incorrect.</td>
<td>• Configure Control Loop Action on Control Loop page.</td>
</tr>
<tr>
<td>Output cycles (turns on and off) too frequently.</td>
<td>• Wrong control mode. PID control selected instead of ON-OFF control.</td>
<td>• Activate ON-OFF control on Output page.</td>
</tr>
<tr>
<td></td>
<td>• The cycle time is set too short.</td>
<td>• Increase Output Cycle Time on Output page.</td>
</tr>
<tr>
<td>Cannot access Security, Monitor, Configuration or Calibration page.</td>
<td>• Password is enabled and incorrect password is supplied.</td>
<td>• Provide the correct user name and password.</td>
</tr>
<tr>
<td>Process value reads incorrectly</td>
<td>• Analog input is configured incorrectly.</td>
<td>• Configure control for appropriate sensor input on Analog Input page.</td>
</tr>
<tr>
<td></td>
<td>• Thermocouple sensor shorted.</td>
<td>• Repair wiring or replace sensor.</td>
</tr>
<tr>
<td></td>
<td>• Process sensor scaled incorrectly.</td>
<td>• Set scaling on Analog Input page.</td>
</tr>
<tr>
<td></td>
<td>• Calibration offset is incorrect.</td>
<td>• Correctly set calibration offset.</td>
</tr>
<tr>
<td></td>
<td>• Sensor is wired incorrectly.</td>
<td>• Wire sensor per wiring section.</td>
</tr>
<tr>
<td></td>
<td>• Controller calibration is incorrect or corrupt.</td>
<td>• Recalibrate controller.</td>
</tr>
<tr>
<td></td>
<td>• Defective controller.</td>
<td>• Repair or replace controller.</td>
</tr>
</tbody>
</table>
Appendix

Specifications

Controller
- Microprocessor based user-selectable control modes
- Single or dual channel universal inputs
- Current transformer inputs to monitor heater currents
- Digital inputs
- Up to four programmable outputs
- Update rates, inputs = 10Hz, outputs = 10Hz

Operator Interface
- Browser based HMI (human machine interface)

Standard Conditions For Specifications
- Ambient temperature 25°C (77°F) ±3°C, rated line voltage, 50 to 60Hz, 0 to 90% RH non-condensing, 15-minute warm-up

Universal Analog Input
- Sample rate: 10 Hz

Thermocouple
- Type J, K, T, N, E, C, (W5), D (W3), PTII (F), R, S, B thermocouple types.
- >20 MΩ input impedance
- Maximum 20 Ω source resistance

RTD
- 2- or 3-wire platinum, 100 Ω
- DIN curve (.00385 curve)
- 250 μA nominal RTD excitation current

Process
- Voltage input ranges
- Accuracy ±10mV ±1 LSD at standard conditions
- Temperature stability ±100 ppm/°C maximum

Digital Input
- Contact closure or voltage input
- Input impedance: 10 kΩ
- Sample rate: 5 Hz
- Resistance/contact input
- Input high state >7 kΩ
- Input low state 0-2 kΩ
- Voltage input
- Input high state 2-36 Vdc
- Input low state 0-1 Vdc

Current Transformer Input
- Input range: 0-50 mA (ac)
- Input impedance: 100 Ω
- Sample rate: 5 Hz

Allowable Operating Ranges

Thermocouple Input
- Calibration accuracy and sensor conformity: ±0.1% of input span ±1°C at standard conditions
- Temperature stability: ±0.2 degree per degree change in ambient for J, K, T, N, E, PTII ±0.5% for C, D, R and S

RTD Input
- Calibration accuracy ±0.1% of input range ±1°C at standard conditions
- Temperature stability: ±0.05 degree per degree change in ambient

Process Input
- Voltage input ranges
- Accuracy ±10mV ±1 LSD at standard conditions
- Temperature stability ±100 ppm/°C maximum

Universal Analog Input
- Sample rate: 10 Hz

Thermocouple
- Type J, K, T, N, E, C, (W5), D (W3), PTII (F), R, S, B thermocouple types.
- >20 MΩ input impedance
- Maximum 20 Ω source resistance

RTD
- 2- or 3-wire platinum, 100 Ω
- DIN curve (.00385 curve)
- 250 μA nominal RTD excitation current

Process
- Voltage input ranges
- Accuracy ±10mV ±1 LSD at standard conditions
- Temperature stability ±100 ppm/°C maximum

Digital Input
- Contact closure or voltage input
- Input impedance: 10 kΩ
- Sample rate: 5 Hz
- Resistance/contact input
- Input high state >7 kΩ
- Input low state 0-2 kΩ
- Voltage input
- Input high state 2-36 Vdc
- Input low state 0-1 Vdc

Current Transformer Input
- Input range: 0-50 mA (ac)
- Input impedance: 100 Ω
- Sample rate: 5 Hz

Allowable Operating Ranges

Type J: -210 to 1,200°C or -346 to 2,192°F
Type K: -270 to 1,372°C or -454 to 2,502°F
Type T: -270 to 250°C or -454 to 482°F
Type N: -270 to 1,250°C or -454 to 2,282°F
Type E: -270 to 800°C or -454 to 1,470°F
Type C (W5): 0 to 2,315°C or 32 to 4,200°F
Type D (W3): 0 to 2,315°C or 32 to 4,200°F
Type PTII (F): -3 to 1,393°C or 25 to 2,545°F
Type R: -50 to 1,393°C or -58 to 3,214°F
Type S: -50 to 1,393°C or -58 to 3,214°F
Type B: 0 to 1,820°C or 32 to 3,308°F
DIN: -200 to 800°C or -328 to 1,470°F
Process: -1,999 to 9,999 units
Output Types

**Open Collector**
- Maximum voltage: 42V = (dc)
- Maximum current: 500 mA
- Class 2 power source required

**Switched DC**
- Supply voltage: 24V = (dc) @ 30 mA
- Supply voltage maximum: 28V = (dc) into an infinite load

**Solid-state Relay**
- Optically isolated
- Zero cross switched
- Without contact suppression
- Minimum load current: 500 µA rms
- 0.5A at 24 to 240V~ (ac), resistive
- 20 VA pilot duty, 120/240V~ (ac), inductive
- Maximum offstate leakage current: 10 µA rms
- Use RC suppression for inductive loads

**Electromechanical Relay, Form A**
- Minimum load current: 10 mA
- 2 A @ 240V~ (ac) or 30V= (dc), resistive
- 125 VA pilot duty, 120/240V~ (ac), inductive
- Electrical life 100,000 cycles at rated current
- Use RC suppression for inductive loads

**Electromechanical Relay, Form C**
- Minimum load current: 10 mA
- 2 A @ 240V~ (ac) or 30V= (dc), resistive
- 125 VA pilot duty, 120/240V~ (ac), inductive
- Electrical life 100,000 cycles at rated current
- Use RC suppression for inductive loads

**Process (Control or Retransmit)**
- Range selectable: 0 to 20 mA, 4 to 20 mA, 0 to 5V= (dc), 1 to 5V= (dc), 0 to 10V= (dc) (Can reverse low and high values.)
- Reverse or direct acting
- 0 to 10V= (dc) voltage output into 1,000 Ω minimum load resistance
- 0 to 20 mA current output into 800 Ω maximum load resistance
- Resolution:
  - dc ranges: 2.5 mV nominal
  - mA ranges: 5 µA nominal
- Calibration accuracy:
  - dc ranges: ±15 mV
  - mA ranges: ±30 µA
- Temperature stability: 100 ppm/°C

Communications

**Ethernet**
- Isolated
- Ethernet RJ 45 connector, 10 base T
- HTTP interface
- DHCP, auto IP or fixed IP addressing

Agency Approvals
- UL®508 File #102269, C-UL®, CSA and CE
  UL® is a registered trademark of the Underwriter’s Laboratories, Inc.
- Submitted to Canadian Standards Association for testing.

Terminals
- Touch-safe
- Compression: Will accept 0.2 to 4 mm² (22 to 12 AWG) wire
- Wire strip length: 6 mm (0.24 in)
- Torque terminal blocks to 0.9. Nm (8 in-lb)

Power
- 24V= (ac/dc) +10%; -15%; 50/60 Hz, ±5%
- Class 2 power source required.
- 14VA maximum power consumption
- Data retention upon power failure via nonvolatile memory

Operating Environment
- 0 to 65°C (32 to 149°F)
- 0 to 90% RH, non-condensing
- Storage temperature: -40 to 85°C (-40 to 185°F)

Dimensions
- Width x height x depth
  42 mm x 118 mm x 128 mm (1.64 in x 4.66 in x 5.06 in)
- DIN rail or chassis mount
  DIN rail spec DIN 50022, 35 mm x 7.5 mm (1.38 in x 0.30 in)

Note: These specifications are subject to change without prior notice.
# Ordering Information

<table>
<thead>
<tr>
<th>Control Type</th>
<th>S or D</th>
</tr>
</thead>
<tbody>
<tr>
<td>S</td>
<td>Single channel</td>
</tr>
<tr>
<td>D</td>
<td>Dual channel</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Auxiliary Inputs</th>
<th>A, 1, 2 or 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>None</td>
</tr>
<tr>
<td>1</td>
<td>Dual digital inputs</td>
</tr>
<tr>
<td>2</td>
<td>One CT input and one digital input</td>
</tr>
<tr>
<td>3</td>
<td>Dual CT inputs (dual channel only)</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Output 1</th>
<th>C, K, F or J</th>
</tr>
</thead>
<tbody>
<tr>
<td>C</td>
<td>Switched dc, open collector</td>
</tr>
<tr>
<td>K</td>
<td>SSR, Form A, 0.5 A</td>
</tr>
<tr>
<td>F</td>
<td>Universal process</td>
</tr>
<tr>
<td>J</td>
<td>Mechanical relay, Form A, 2 A</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Output 2</th>
<th>A, C, K or E</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>None</td>
</tr>
<tr>
<td>C</td>
<td>Switched dc, open collector</td>
</tr>
<tr>
<td>K</td>
<td>SSR, Form A, 0.5 A</td>
</tr>
<tr>
<td>E</td>
<td>Mechanical relay, Form C, 2 A</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Output 3</th>
<th>A, C, K, F* or J</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>None</td>
</tr>
<tr>
<td>C</td>
<td>Switched dc, open collector</td>
</tr>
<tr>
<td>K</td>
<td>SSR, Form A, 0.5 A</td>
</tr>
<tr>
<td>F*</td>
<td>Universal process*</td>
</tr>
<tr>
<td>J</td>
<td>Mechanical relay, Form A, 2 A</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Output 4</th>
<th>A, C, K or E</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>None</td>
</tr>
<tr>
<td>C</td>
<td>Switched dc, open collector</td>
</tr>
<tr>
<td>K</td>
<td>SSR, Form A, 0.5 A</td>
</tr>
<tr>
<td>E</td>
<td>Mechanical relay, Form C, 2 A</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Data Logging</th>
<th>0 or 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>None</td>
</tr>
<tr>
<td>1</td>
<td>16 megabytes of on-board memory</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Custom options</th>
<th>AA or BB</th>
</tr>
</thead>
<tbody>
<tr>
<td>AA</td>
<td>Watlow logo</td>
</tr>
<tr>
<td>BB</td>
<td>No logo</td>
</tr>
</tbody>
</table>

*Note: Available only if “F” output option is selected for Output 1.*

**Accessories**

- 120~(ac) input, 24~(dc) output, Class 2 power supply — 0830-0474-0000
- 12 pin removable screw terminal connector — 0836-1279-0012
- 14 pin removable screw terminal connector — 0836-1280-0014
Declaration of Conformity

Series PD
Watlow Winona, Inc.
1241 Bundy Blvd.
Winona, MN 55987 USA

Declares that the following product:

Designation: Series PD
Model Numbers: PD (D or S) (1, 2 or 3) – (C, F, J or K) (A, C, E or K) (A, C, F, J or K) (A, C, E or K) – (0 or 1) (any three letters or numbers)
Classification: Temperature control, Installation Category II, Pollution degree 2
Rated Voltage: 24V (ac or dc)
Rated Frequency: 50 or 60 Hz
Rated Power Consumption: 14VA maximum

Meets the essential requirements of the following European Union Directives by using the relevant standards shown below to indicate compliance.

89/336/EEC Electromagnetic Compatibility Directive

EN 61000-4-3: 1997: Radiated Field Immunity
EN 61000-4-4: 1995: Electrical Fast-Transient / Burst Immunity
EN 61000-4-6: 1996: Conducted Immunity
EN 61000-4-11: 1994: Voltage Dips, Short Interruptions and Voltage Variations Immunity
EN 61000-3-2: ED.2. 2000: Harmonic Current Emissions

73/23/EEC Low-Voltage Directive

EN 61010-1: 2001 Safety Requirements of electrical equipment for measurement, control and laboratory use. Part 1: General requirements

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Winona, Minnesota, USA
Place of Issue

General Manager
Title of Authorized Representative
April 2003
Date of Issue

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